bintec-elmeg Manual





# **ASTM Interface**

bintec-Dm 721-I

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Manual bintec-elmeg

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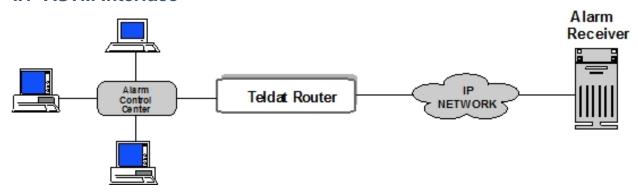
# **I Related Documents**

bintec-Dm 772-I Common Configuration for Interfaces

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## **Chapter 1 Introduction**

## 1.1 ASTM Interface



In a work scenario like the one above, the messages generated by the security and surveillance devices (alarm centers) must be sent over an IP-based data network. To be able to do this, two facilities will need to be implemented. First, you have to define a method for transporting messages over the network; and second, you have to specify a data conversion method that converts data from the format delivered by the surveillance device (alarm center) to the format specified in the method defined for transport.

The first objective is to implement a transport protocol for sending general data over IP (Internet Protocol) networks.

The method used for this is called Trivial Message Transfer Protocol (TRMTP). In this method, each message is treated separately from the other messages that are sent.

This protocol has been designed to be easy to implement, not to consume excessive resources and not to significantly increase the workload of the devices that will use it. Its most widespread use will be to send alarm messages between devices.

To keep load and resource consumption down, it is implemented over UDP (User Datagram Protocol) in IP.

Here are some of the TRMTP protocol's characteristics:

- It ensures that all information messages reach the other end (CONFIRMATION MODE).
- It ensures that duplicated messages are detected at reception and discarded (CONFIRMATION MODE).
- It ensures that messages arrive in the correct order (CONFIRMATION MODE).
- It includes a datagram sending service that, while not fully guaranteeing delivery, is faster (DATAGRAM MODE).
- It is non-connection-oriented.
- It is bi-directional (a device can both send and receive messages).

The second objective is to describe a conversion method to be able to send data received through an asynchronous serial interface using the TRMTP protocol defined previously.

The converter will be defined as ASYN-TRMTP and the interface supporting this conversion will be called ASTM (ASynchronous Transport Message).

## 1.1.1 Functionality

The defined converter will function as a PAD or PDA (Packet Assembler/Dissembler). These systems basically use set rules to package data received through the asynchronous interface and send them in frames or messages through the packet-oriented interface. They also perform the reverse process for data received from the packet-orientated interface.

## 1.1.2 TRMTP -> ASYNCHRONOUS Conversion

The following defines the rules that the converter will refer to in order to generate TRMTP messages with the data received through the asynchronous interface.

Since the nature of the data traffic basically consists of messages sent between devices and not a continuous flow of data, a software flow control system has not been defined. The devices are considered to have sufficient memory to allow them to receive the messages in full, and the functions of flow control and errors are handled by higher-level protocols between machines using the transport system.

To keep the design simple and recover device resources as quickly as possible, the system discards the received packets when it is congested, both globally in the device and in the output queues to the interface. To avoid these congestion situations as much as possible, it is important to define enough memory for these tasks.

#### 1.1.2.1 Congestion in the device

The device is considered congested when it has insufficient memory to store the received TRMTP messages before their transmission to an asynchronous serial port, either because it has insufficient buffers to store them, or the outgoing gueues to the serial interface are full.

- In the TRMTP DATAGRAM service, the received DGM messages are discarded and not forwarded to the interface.
- In the TRMTP WITH CONFIRMATION service, the received INF messages are discarded and not confirmed. NAK
  can be used to respond or not respond.

#### 1.1.2.2 TRMTP Service Down

In this case, messages are not received from the TRMTP service.

## 1.1.2.3 Asynchronous Interface Down

The interface is considered down or out of order when physical signals indicate that the device connected to the interface is not functioning.

- In the TRMTP DATAGRAM service, the received DGM messages are discarded and not forwarded to the interface.
- In the TRMTP WITH CONFIRMATION service, the received INF messages are discarded and not confirmed. NAK
  can be used to respond or not respond.

### 1.1.2.4 Both Asynchronous Interface and TRMTP Service Operative

The interface is considered operative when physical signals indicate that the device connected to the interface is functioning.

Different priority levels are not defined for INF and DGM messages. The data must therefore respect the chronological arrival order when forwarded to the serial interface.

- In the TRMTP DATAGRAM service, the received DGM messages are sent to the outgoing asynchronous interface queues.
- In the TRMTP WITH CONFIRMATION service, the data received in INF or DGM messages is sent to the outgoing asynchronous interface queues.

## 1.1.3 ASYNCHRONOUS -> TRMTP Conversion

The following defines the rules that the converter will refer to in order to generate TRMTP messages with the data received through the asynchronous interface.

Since the nature of the data traffic basically consists of messages sent between devices and not a continuous flow of data, a software flow control system has not been defined. The devices are considered to have sufficient memory to receive the messages in full, and the functions of flow control and errors are handled by higher-level protocols between devices using the transport system.

To keep the design simple and recover device resources as quickly as possible, the system discards the received packets when it is congested, both globally in the device and in the output queues to the interface. To avoid these congestion situations as much as possible, it is important to define enough memory for these tasks.

#### 1.1.3.1 Congestion in the device

The device is considered congested when it has insufficient memory to create TRMTP messages from the data received through the asynchronous serial interface. If the incoming asynchronous interface queues become full, characters are lost. It is therefore important to make the queues large enough to avoid losing information.

#### 1.1.3.2 TRMTP Service Down

In this case, the messages generated in the conversion are discarded by the TRMTP service and lost.

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## 1.1.3.3 Asynchronous Interface Down

The interface is considered down or out of order when physical signals indicate that the device connected to the interface is not functioning. In this case, data from the asynchronous serial interface is not received.

## 1.1.3.4 Both Asynchronous Interface and TRMTP Service Operative

The characters received by the asynchronous serial port are queued in a buffer and a TRMTP message with the contents of the buffer is generated when any of the following conditions is met.

- The buffer is filled with the value defined in the TRMTP service N1 parameter.
- The received character causes the buffer to send according to the CHRSND parameter you define for the conversion.
- There are characters in the buffer and the TMRSND send timer expires when the last character is received.

Once the buffer is ready to send, there is a request to generate the TRMTP message.

- In the TRMTP DATAGRAM service, there is a request to send a DGM message.
- In the TRMTP WITH CONFIRMATION service, there is a request to send an INF message.

## 1.1.4 Asynchronous Interface Parameters

The asynchronous interface has the following configurable parameters:

- SPEED: Speed of the asynchronous serial interface. You can set this to between 300 and 64000 bps. The default value is 9600.
- DATA BITS (BDATA): Number of data bits per character. Since this system tries to send octets, the default value is 8. The possible values are 5, 6, 7 or 8.
- STOP BITS (BSTOP): Number of STOP bits per character. The default value is 1. The possible values are 1 or 2.
- PARITY: Type of parity used. By default this will NOT be used. The possible values are EVEN, ODD, MARK, SPACE or NONE.

## 1.1.5 Conversion Parameters

The following are the configurable parameters for the ASYN-TRMTP converter:

- CHRSND: Character that triggers the sending of data. This parameter is configurable and actually based on parameter 3 from the X.3 standard. Its value can be between 0 and 255 (0xFF); any bits set to 1 indicate the characters that can trigger data transmission. The default is 0, meaning that no character triggers data transmission. Here is an explanation of the meaning of each bit:
  - 0x00 No character triggers data transmission.
  - 0x01 (A Z, a z, 0 9) trigger data transmission.
  - 0x02 CR triggers data transmission.
  - 0x04 ESC, BEL, ENQ, ACK trigger data transmission.
  - 0x08 DEL, CAN, DC2 trigger data transmission.
  - 0x10 ETX, EOT trigger data transmission.
  - 0x20 HT, LF, VT, FF trigger data transmission.
  - 0x40 Other characters (0x00 0x1F) not previously defined.
  - 0x80 Other characters (0x20 0x7F) not previously defined.
- TMRSND: Inactivity timer that triggers the sending of data. It starts whenever a character is received through the asynchronous interface. This parameter is configurable and is actually based on parameter 4 from the X.3 standard. Its value can range from 0 to 65535. The units of the timer are 1/20 of a second. The default value is 0, which deactivates the timer; although this does not actually happen because if there is no send character defined either, a 60-second inactivity timer is used to send the buffer.

## **Chapter 2 Configuration**

## 2.1 Assigning the ASTM Interface

The ASTM interface operates on a serial line. Therefore, in order to add an ASTM interface you need to assign one of the router's serial lines as ASTM through the SET DATA-LINK command found in the general configuration menu. To do this, enter PROCESS 4 or just P 4 at the asterisk (\*) prompt. This will take you to the *Config>* configuration prompt.

```
*p 4
Config>
```

Then you need to enter the SET DATA-LINK command.

```
Config>set data-link astm serial0/0 Config>
```

"SerialX/X" interfaces are compatible with the ASTM protocol.

If the router has only one WAN line, you will not be asked which interface you want to use (as shown in the following example):

```
Config>set data-link asdp
Config>
```

Once you have assigned the interface, you can configure it. However, for the changes to take effect and to be able to monitor said interface, you need to save the configuration and restart the device.

## 2.2 ASTM Configuration Commands

Follow the steps outlined here to access the configuration procedure:

(1) At the asterisk (\*) prompt, enter PROCESS 4 or just P 4. This will take you to the configuration prompt Config>.

```
*p 4
Config>
```

If the Config> prompt does not immediately appear, press enter again.

(2) Then, enter the **NETWORK** command, followed by the name of the ASTM interface that you configured previously. This is generically known as <ifc>.

```
Config>network <ifc>
-- ASTM Interface Configuration --
ASTM-ifc Cfg>
```

If, for example, the interface was serial0/0, it would look like this:

```
Config>network serial0/0

-- ASTM Interface Configuration --
ASTM-serial0/0 Cfg>
```

Some commands are common to all the device's interfaces. These commands are described in the manual on configuring common interfaces (bintec-Dm 772-I Common Configurations for Interfaces).

This chapter lists and describes the ASTM configuration commands. All ASTM configuration commands must be entered from the ASTM prompt (ASTM-ifc Cfg>).

Command	Function
? (HELP)	Lists configuration commands or associated parameters within a command.
RESTORE	Restores the default configuration used in the ASTM interfaces.
SET	Configures specific interface parameters.
EXIT	Returns to the Config> prompt.

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## 2.2.1 ? (HELP)

You can use the ? (HELP) command to display a list of available commands at the normal prompt level. Likewise, by typing a question mark (?) after a specific command name, you can learn which options are available for that command.

#### Syntax:

```
ASTM-serial0/0 Cfg>?
```

#### Example:

```
ASTM-serial0/0 Cfg>?

restore Restore ASTM default configuration
set Configure ASTM parameters
exit

ASTM-serial0/0 Cfg>
```

#### 2.2.2 RESTORE

Use the **RESTORE** command to load the interface's default values to the configuration.

#### Syntax:

```
ASTM-serial0/0 Cfg>restore
```

#### Example:

```
ASTM-serial0/0 Cfg>restore
ASTM-serial0/0 Cfg>
```

#### 2.2.3 SET

This command is used to configure different interface-specific parameters.

#### Syntax:

```
ASTM-serial0/0 Cfg>set ?

character-send Configure the message send character

data-bits Set number of bits per character

local-port Configure local UDP port

mode Configure the type of service used

n1 Configure TRMTP data field size

n2 Configure maximum number of TRMTP retransmissions

parity Set character parity

remote-ip Configure the remote device IP address

remote-port Configure the remote device UDP port

speed Set speed

stop-bits Set number of stop bits per character

t1 Wait time for a TRMTP message response

t2 TRMTP error recuperation timer

t3 TRMTP transmission inactivity timer

t4 TRMTP reception inactivity timer

t4 TRMTP reception inactivity timer

timer-send Configure the message timer-sendCHARACTER-SEND
```

### 2.2.3.1 SET CHARACTER-SEND

Configures the character whose reception causes messages to be sent. This parameter tells the ASTM-TRMTP converter to send the message with the received data, including the send character when it is received. Allowed values range from 0 to 255. A 0 value means that there is no character to trigger sending messages. In this case, they are only sent if the sending timer expires or if the N1 value for received data waiting to be sent is exceeded. The value is a bit mask, where each bit indicates the characters allowed to trigger the sending. The default value is 0.

- 0x00 (0) No character triggers data transmission.
- 0x01 (1) (A Z, a z, 0 9) trigger data transmission.
- 0x02 (2) CR triggers data transmission.
- 0x04 (4) ESC, BEL, ENQ, ACK trigger data transmission.

- 0x08 (8) DEL, CAN, DC2 trigger data transmission.
- 0x10 (16) ETX, EOT trigger data transmission.
- 0x20 (32) HT, LF, VT, FF trigger data transmission.
- 0x40 (64) Other characters (0x00 0x1F) not previously defined.
- 0x80 (128) Other characters (0x20 0x7F) not previously defined.

## Example:

```
ASTM-serial0/0 Cfg>set character-send 2
ASTM-serial0/0 Cfg>
```

## **2.2.3.2 SET DATA-BITS**

Sets the number of data bits per character in the asynchronous port. Allowed values are 5, 6, 7 or 8 bits/character. The default value is 8.

#### Example:

```
ASTM-serial0/0 Cfg>set data-bits 8
ASTM-serial0/0 Cfg>
```

#### 2.2.3.3 SET LOCAL-PORT

This parameter allows you to configure the local UDP port that will receive the TRMTP messages for this interface. Valid values range from 0 to 65535. The default port is 20000.

### Example:

```
ASTM-serial0/0 Cfg>set local-port 20000
ASTM-serial0/0 Cfg>
```

#### 2.2.3.4 SET MODE

Sets the mode or type of service that the ASTM-TRMTP converter will use to send messages. DATAGRAM mode does not ensure that they reach their destination. CONFIRMED mode awaits confirmation of the destination before sending a new message. The default mode is datagram.

## Syntax:

```
ASTM-serial0/0 Cfg>set mode ?

confirmed

datagram
```

## 2.2.3.4.1 Set Mode Confirmed

### Example:

```
ASTM-serial0/0 Cfg>set mode confirmed
ASTM-serial0/0 Cfg>
```

#### 2.2.3.4.2 Set Mode Datagram

#### Example:

```
ASTM-serial0/0 Cfg>set mode datagram
ASTM-serial0/0 Cfg>
```

#### 2.2.3.5 SET N1

Configures the N1 parameter or maximum data field size for messages that can be sent or received by TRMTP. Allowed values range from 1 to 1600 octets. The default value is 1500.

## Example:

```
ASTM-serial0/0 Cfg>set n1 1600
ASTM-serial0/0 Cfg>
```

#### 2.2.3.6 SET N2

Configures the N2 parameter or maximum number of retransmissions allowed per message in TRMTP. This parameter only makes sense in CONFIRMED mode. Allowed values range from 0 to 65335. Setting a 0 or 1 value indicates no retransmission. The default value is 3.

#### Example:

```
ASTM-serial0/0 Cfg>set n2 5
ASTM-serial0/0 Cfg>
```

#### **2.2.3.7 SET PARITY**

Sets the parity that is used in a character on the asynchronous port. Allowed values are EVEN, ODD, MARK, SPACE or NONE. The default value is NONE.

#### Syntax:

```
ASTM-serial0/0 Cfg>set parity ?

even

mark

none

odd

space

ASTM-serial0/0 Cfg>
```

## Example:

```
ASTM-serial0/0 Cfg>set parity none
ASTM-serial0/0 Cfg>
```

#### 2.2.3.8 SET REMOTE-IP

This parameter lets you configure the remote device's IP address to which the TRMTP protocol is going to send the messages.

### Example:

```
ASTM-serial0/0 Cfg>set remote-ip 192.168.0.1
ASTM-serial0/0 Cfg>
```

#### 2.2.3.9 SET REMOTE-PORT

This parameter allows you to configure the remote device UDP port to which the TRMTP protocol is going to send the messages to. Allowed values range from 0 to 65535. The default port is 20000.

#### Example:

```
ASTM-serial0/0 Cfg>set remote-port 20000
ASTM-serial0/0 Cfg>
```

#### 2.2.3.10 SET SPEED

This command sets the interface's reception and transmission speed. Allowed values range from 300 to 64000 bps. The default is 9600 bps.

## Example:

```
ASTM-serial0/0 Cfg>set speed 1200
ASTM-serial0/0 Cfg>
```

## **2.2.3.11 SET STOP-BITS**

Configures the number of Stop bits per character on the asynchronous port. Allowed values are 1 or 2 Stop bits/character. The default value is 1.

## Example:

```
ASTM-serial0/0 Cfg>set stop bits 1
ASTM-serial0/0 Cfg>
```

#### 2.2.3.12 SET T1

Sets the TRMTP protocol T1 parameter, which indicates the wait timer value for a response to a TRMTP message. After this has expired, the message is transmitted again. Allowed values are from 1 second to 18 hours, 12 minutes and 15 seconds. The default value is 30 seconds.

#### Example:

```
ASTM-serial0/0 Cfg>set t1 3h12m3s
ASTM-serial0/0 Cfg>
```

#### 2.2.3.13 SET T2

Sets the TRMTP protocol T2 parameter, which indicates the TRMTP error recuperation timer value. When a transmission error occurs, the TRMTP system for this interface becomes inactive. Once the T2 has timed out, the system becomes active once more and from here tries to synchronize with the receptor again when it is going to send a confirmation message. Allowed values range from 1 second to 18 hours, 12 minutes and 15 seconds and should be greater than T1. The default value is 300 seconds.

#### Example:

```
ASTM-serial0/0 Cfg>set t2 4h14m30s
ASTM-serial0/0 Cfg>
```

#### 2.2.3.14 SET T3

Configures the TRMTP protocol T3 parameter. Indicates the inactivity timer value between sent TRMTP confirmed messages. This timer sets the inactivity time between sent messages. This starts up each time a confirmed TRMTP message is sent. When it expires, the TRMTP transmitter sends an EOT order to the remote end indicating that the next confirmed message will be preceded by a synchronization phrase. Allowed values are from 0 seconds to 18 hours, 12 minutes and 15 seconds and should be greater than T2. A 0 value indicates that an EOT is always sent after each confirmed TRMTP message. The default value is 0 seconds.

#### Example:

```
ASTM-serial0/0 Cfg>set t3 200
ASTM-serial0/0 Cfg>
```

#### 2.2.3.15 SET T4

Configures the TRMTP protocol T4 parameter. Indicates the inactivity timer value between received TRMTP confirmed messages. This timer sets the inactivity time between received messages. It starts up each time a confirmed TRMTP message is received. When it expires, the TRMTP receiver enters idle state and the next confirmed message to be received must be preceded by a synchronization phase. Allowed values range from 1 second to 18 hours, 12 minutes and 15 seconds. Setting a similar value to the T3 parameter is advisable, though not absolutely necessary. The default value is 300 seconds.

## Example:

```
ASTM-serial0/0 Cfg>set t4 200
ASTM-serial0/0 Cfg>
```

## **2.2.3.16 SET TIMER-SEND**

Sets the message sending timer. This parameter tells the ASTM-TRMTP converter to send the message with the received data if the configured inactivity time has expired since the last data was received through the interface. Admitted values range from 0 to 65535 expressed in units of 1/20 of a second. A 0 value indicates that a 60-second default value is used. The default value is 0.

#### Example:

```
ASTM-serial0/0 Cfg>set timer-send 1
ASTM-serial0/0 Cfg>
```

## 2.2.4 **EXIT**

Use the **EXIT** command to return to the previous prompt.

#### Syntax:

ASTM-serial0/0 Cfg>exit

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## Example:

ASTM-serial0/0 Cfg>exit Config>

## **Chapter 3 Monitoring**

## 3.1 **ASTM Monitoring Commands**

Follow the steps outlined below to access the ASTM monitoring procedure:

(1) At the asterisk (\*) prompt, enter PROCESS 3 or just P 3. This will take you to the monitoring prompt (+).

```
*p 3 +
```

(2) At the plus (+) prompt, enter the **NETWORK** command followed by the name of the interface associated with the previously configured ASTM device, which we will generically call < ifc>.

```
+network <ifc>
-- ASTM Console --
ASTM-ifc+
```

If, for example, the interface was serial0/0, it would look like this:

```
+ network serial0/0
-- ASTM Console --
ASTM-serial0/0+
```

This chapter lists and describes the ASTM monitoring commands. All ASTM monitoring commands must be entered at the ASTM prompt (ASTM-ifc >).

Command	Function
? (HELP)	Lists available commands or command options.
CLEAR	Clears the link counters.
LIST	Displays link counter information.
EXIT	Exits the ASTM monitoring environment.

## 3.1.1 ? (HELP)

You can use the ? (HELP) command to display a list of available commands at the normal prompt level. Likewise, by typing a question mark (?) after a specific command name, you can learn which options are available for that command.

## Syntax:

ASTM-ifc+?

### Example:

```
ASTM-serial0/0+?

clear Initialize link counters

list Show statistics for link data level

exit

ASTM-serial0/0+
```

## **3.1.2 CLEAR**

Use the **CLEAR** command to clear the link counters.

## Syntax:

ASTM-ifc+clear

## Example:

```
ASTM-serial0/0+clear
ASTM-serial0/0+
```

## 3.1.3 LIST

Use the LIST command in the monitoring process to display data-link level statistics.

## Syntax:

ASTM-ifc+list

#### Example:

```
ASTM-serial0/0+list
Bytes sent to interface
                              : 800
Bytes received from interface : 971
Bytes sent over INF messages
                               : 971
Bytes received over INF messages: 800
Bytes sent over DGM messages
Bytes received over DGM messages : 0
INF messages sent : 161
INF messages received : 208
DGM messages sent
DGM message received
TST messages received
EOT messages received
ACK messages received
                              : 162
NAK messages received
                              : 0
T1 Timeouts detected
                              : 0
T2 Timeouts detected
                              : 0
T3 Timeouts detected
                              : 1
T4 Timeouts detected
                              : 0
N2 overflows detected
                             : 0
Error or congestion detected : 0
ASTM-serial0/0+
```

The meaning of each field is:

Bytes sent to interface

Bytes received from interface

Bytes sent over INF messages

Bytes received over INF messages

Bytes sent over DGM messages

Bytes received over DGM messages

INF messages sent

INF messages received

DGM messages sent

DGM message received

TST messages received

EOT messages received

201 11100000900 10001100

ACK messages received

NAK messages received

T1 Timeouts detected

T2 Timeouts detected

T3 Timeouts detected

T4 Timeouts detected

N2 overflows detected

Error or congestion detected

No. of bytes sent to the interface.

No. of bytes received from the interface.

No. of bytes sent in INF messages or confirmed.

No. of bytes received in INF messages or confirmed.

No. of bytes transmitted in DGM messages or datagrams

No. of bytes received in DGM messages or datagrams.

INF or confirmed messages sent.

INF or confirmed messages received.

DGM or confirmed messages sent.

INF or confirmed messages received.

Synchronized TST messages received.

EOT end of transmission messages received.

ACK messages received.

NAK messages received.

T1 timeouts detected.

T2 timeouts detected.

T3 timeouts detected.

T4 timeouts detected.

Thirteduce detected.

Excessive retransmission detected.

Transmission error or congestion detected.

## 3.1.4 **EXIT**

Use the **EXIT** command to return to the previous prompt.

## Syntax:

ASTM-ifc+exit

#### Example:

ASTM-serial0/0+exit

## 3.2 Viewing ASTM interface statistics

You can use the **DEVICE** command to view statistics for ASTM devices. To do this, enter the **DEVICE** command and the interface name at the plus (+) prompt as shown below:

#### Syntax:

+device <ifc>

#### Example:

```
+device serial0/0
                            Auto-test Auto-test Maintenance
Interface CSR Vect valids failures failures serial0/0 FA200A00 5E 0 0 0
Interface DTE
 Circuits: 105 106 107 108 109 125 141
 Nicknames: RTS CTS DSR DTR DCD RI LL
  State: ON OFF OFF ON OFF --- OFF
                         1200
Speed (bps)
Throughput (bps)
                        1575
2160
Last throughput (bps) =
                          8
Bits per character =
                            1
Stop bits
                = NONE
Parity selected
                          0
Parity errors
Data errors
                            0
Overrun errors = 0

Last reset = 2 hours 54 minutes 41 seconds
```

Interface Interface assigned by software, during the initial configuration.

CSR Location of the status control register memory for the ASTM interface.

Vect Interrupt vector.

Auto-test valids

No. of times the ASTM interface passed the auto-test.

Auto-test failures

No. of times the ASTM interface failed the auto-test.

Maintenance failures No. of maintenance failures.

Indicates interface behavior (DTE or DCE).

Circuit Circuits in use.

Nickname Physical signal name.

StateState of circuits, signals and pin assignment (ON or OFF).SpeedNormal speed for the configured ASTM interface line.ThroughputInterface throughput expressed in bits/seconds.

Last throughput Interface's last measured throughput expressed in bits/seconds.

Bits per character No. of Data bits per character configured.

Stop bits No. of Stop bits configured.

Parity selected Parity per character configured.

Parity errors Parity errors detected.

Data errors Framing or synchronization errors detected.

Overrun errors Overrun errors detected.

Last reset Time elapsed since the last port reset.